# **On Classification of Sleep Mechanism EEG Data**

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**ABSTRACT:** We utilize a recent form of the Nested Cavities (abbr. NC) classifier [1] from which a powerful new classification approach emerged. In this application there are many outliers in the datasets [5] which judiciously removed. Further, working on the classification of Stage 3 we found wide dispersal in the data. After considerable experimentation we concluded that, between Stage2 and Stage3 some of the data is misclassified. By including some of the Stage2 data with values very close to those of Stage3 and forming a New-Stage 3 ALL nine of the measured variables have tight value ranges and the whole data set visually appears as a well-defined cluster. In turn, accurate classification rules are obtained which had not been possible for the original partition into stages. These findings are explained, motivated and analyzed here.

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#### 1. Introduction

Classification is a basic task in data mining and pattern recognition [2]. From insight gained the NC classifier [3] a new step emerges significantly improving the classification. When the classifier either fails to converge or the rule is either very complex or inaccurate, the NC classifier discovers the dataset's structure partitioning it into distinct subcategories which, in turn, can be more simply and accurately classified [1].

There are many outliers in the datasets [5] which we decided to judiciously remove. Further, working on the classification of Stage3 we found wide dispersal in the data. After considerable experimentation we came to the conclusions that, at least between Stage2 and Stage3 some of the data has have been misclassified. By including some of the Stage2 data with values very close to those of Stage3 data and forming a New-Stage 3 ALL nine of the measured variables have tight value ranges and the whole data set visually appears as a well-defined cluster. In turn, accurate classification rules are obtained which had not been possible for the original partition into stages. These findings are explained, motivated and analyzed in this paper. Our thesis then is that some of the data has been misclassified in the original stage partition. This data is identified and new Stage 3 sets are formed whose classification reveals narrow range values of the measured waives providing a much clearer understanding of the sleep mechanism's dynamics. The presentation is intuitive and technical details of the implementation are not elaborated.



Figure 1. Construction of enclosure for the Nested Cavities algorithm



Figure 2. Slp61 dataset-Original stage 3 with 103 data entries, note outliers

## 2. Classification Algorithm

With parallel coordinates (abbr.  $\parallel$ -coords) [4], a dataset *P* with *N* variables is transformed into a set of points in *N* dimensional space. In this setting, the designated subset *S* can be described by means of a hyper surface which encloses just the points of *S*. The description of such a hypersurface provides a rule for identifying, within an acceptable error, the elements of *S*. The use of Parallel Coordinates also enables *visualization of the rule*.



Figure 3. After cropping outliers there are 70 data entries



Figure 4. After classification efforts a new subset emerges containing the cropped stage 3 and data ONLY from stage 2. Note that this data has the highest variable values of those in stage 2 and which are completely and uniformly within the range of values in the cropped stage 3. We form a new stage 3







Figure 6. Perfect Classification for New Stage 33. The simple rule shown returns exactly the same number of data entries

The first "wrapping" S1 is the convex hull of the points of S which also includes some points of P"S. The second wrapping S2 is the convex hull of these points and it includes some points of S which are enclosed with the third wrapping S3. To simplify the wrappings are shown as convex hulls rather than as approximations. Here the selected set is

$$S = (S1 - S2) \cup (S3 - S4)$$
 where  $S4 = /0$ .

At first the algorithm determines a tight upper bound for the *dimension R of S*. For example, P may be a 3-dimensional set of points but all point of S may be on a plane; in which case S has dimension 2. Once R is determined R variables out of the N are chosen and ordered according to their predictive value and the construction process, schematically shown in Figure 1, operates only on these R selected variables.

The algorithm decomposes P into nested subsets, hence the name **Nested Cavities** (abbr. **NC**) for the classifier. The nested subsets are disjoint so they are *partitions* of P. Basically, the "*wrapping*" algorithm produces a convex-hull approximation; the technical details are not needed here. The efficiency of the version implemented here is due to the use of the R-coords representations of N-dimensional objects [4] applied in the description of the resulting hypersurface. It can and does happen that the process does not converge when P does not contain sufficient information to characterize S. It may also happen that S is so "*porous*" (i.e. sponge-like) that an inordinate number of iterations are required. The results (precision of rule) obtained by the **NC** classifier applied to bench-mark datasets were the most accurate when compared to those obtained by 22 other well-known classifiers (see [3]). The overall computational complexity is O(N2 | P |) where N is the number of variables and |P| is the number of points in P.

#### 3. Simulation

### 3.1 Dataset

The raw EEG data were taken from the Physionet (MITBIH) Polysomnographic database. The subjects are male with an average age of 24-42 years. The data is taken with a sampling rate of 250 Hz and ADC resolution of 12 bits. While traditional EEG channels for sleep recording are placed either at C3-A2 or C4-A1 according to the 10-20 system for placement of EEG electrodes on the scalp [2-3]. The EEG recordings were taken from channels C3-O1, C4-A1 and O2-A1. The data are first converted from the .mat There are many outliers in the datasets which we decided to judiciously remove. The Slp61 dataset-Original stage 3 has 103 data entries, note outliers in Figure 2. We then cropped outliers so that there are 67 data entries Figure 3. Further, working on the classification of *Stage* 3 we found wide dispersal in the data. After considerable experimentation we e concluded that between Stage2 and Stage3 some of the data has have been misclassified.

## 3.2 Data Preprocessing

The single sided scaled amplitude spectrum of a real-valued time domain signal is computed for each harmonic parameter. The EEG is first filtered with a level 5 Butterworth high pass filter with cut-off frequencies between 0.5-30 Hz and then by a band stop filter on the 50-60Hz frequencies. The signal is further filtered using the Lab VIEW Wavelet De-noise. It performs noise reduction for 1D signals by using the discrete wavelet transform (DWT) or un-decimated wavelet transform (UWT). The transform used for the system is DWT using db04 wavelet with 7 levels and soft threshold.

#### 3.3 Patitioning into sub- categoris

The EEG sleep dataset from [5] has been a real classification challenge. It has 9 variables, 760 observations in average and 5 stages consisting of wake (stage 0), light sleep (stage 1, 2), slow wave sleep (stages 3 and 4) and paradoxical sleep also known as the REM sleep [6]. The NC classifier was applied to the 11 patients (slp03, slp04, slp14, slp16, slp45, slp 48, slp59, slp60, slp61, slp66 and slp67) EEG datasets. We found stage 3 of patient 61 is the most informative dataset.

#### 3.4 Forming a New-Stage

We then form a New-Stage 3 ALL nine of the measured variables have tight value ranges and the whole data set visually appears as a well-defined cluster. In turn, accurate classification rules are obtained which had not been possible for the original partition into stages.

After classification efforts a new subset emerges containing the cropped stage 3 and data ONLY from stage 2. Note that this data has the highest variable values of those in stage 2 and which are completely and uniformly within the range of values in the cropped stage 3. We form a new stage 3. The new stage called 33. Proceeding with its classification is shown in Figure 6. The

schematic in Figure 7 clarifies the partition.

file to ASCII file before extracting 30-second epochs from the EEG data [10]. Rechtschaffen and Kales' scoring manual determines the sleep characteristic features of non-rapid eye movement (NREM) and REM sleep. NREM sleep was divided into four stages namely: transitional sleep (stage 1), light sleep (stage 2), slow wave sleep (stages 3 and 4) and paradoxical sleep also known as the REM sleep [4-5]. Thus to simplify sleep staging the research used 4 stages wake, LS, SWS, and REM. The signals are filtered using a 5th order Butterworth band pass filters to separate the signal into different harmonic frequencies. Signals are separated into Beta 2 (20-45Hz), Beta 1 (12-20Hz), Alpha (8-12Hz), Theta (4-8Hz), Delta 2 (2.5-4Hz) and Delta 1 (0.5-2.5Hz).

Stage	Beta1	Beta2	Alphal	Alpha2	Theta	Delta	Spindle	Kcomp	Sawtooth
0	0.36078	0.44672	0.10169	0.08109	0.07665	0.11168	0.03433	0.062221	0.045376
1	0.55986	0.60903	0.30639	0.47445	0.32015	0.27198	0.46883	0.21402	0.0173
1	0.27792	0.3512	0.058289	0.21874	0.037884	0.046695	0.44358	0.263298	0.013428
2	0.97828	0.89805	0.315724	0.163	0.179392	0.274043	0.06195	0.497863	0.770415
3	0.64884	0.92269	0.370132	0.09381	0.276664	0.392133	0.0733	0.405085	0.969229
3	0.54641	0.77828	0.091612	0.00772	0.22529	0.311088	0.13842	0.413108	0.712608

Table 1. Dataset Sample

## 7. Conclusion

Research on the automation of sleep stage classification, particularly single channel EEG, has been a challenge for many years. Our findings show that there are many outliers in the Physionet (MITBIH) Polysomnographic database which, we discovered after considerable experimentation, have been misclassified. This data is identified and new Stage 3 sets are formed whose classification reveals narrow range values of the measured waives providing a much clearer understanding of the sleep mechanism dynamics.

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