

## **Editorial**

We have now released the first issue of the thirteenth volume of the **Journal of Intelligent Computing**. This issue has the below described research.

In the opening paper on “**Mobile robot guidance and control systems using fixed potentials**”, The authors have studied the mobile robot guidance and control system with simulation. To do it the authors have assigned the environment with fixed potentials using the aim we have fixed. In the next step, the authors have used a potential field method that is fixed the goal pint fixed repulsion points.

In the next paper on “**Testing framework for the transport systems**”, the authors used the APIS process to address the testing framework of the CCS which is used in the transport system. Further they have verified and validated the product using technical compatibility and safety procedures

In the last paper on “**Smart traffic signals in the road intersections and its impact of analysis**”, the authors have developed a system for smart traffic signals which can help to record vehicle movements in the intersections. This system allowed to record crashes of the vehicles in the intersection and analyse how it has happened and shown the holding reasons of the events.

We will come up with more research in the next issues.

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