

## **Editorial**

We bring the first issue of the **Journal of Information Security Research** with the below described research.

In the first paper on “**PID control for Robot System with internal motors**”, the authors have presented a new PID control based on a new algorithm for robot system. The robust fractional order sliding with proper control is used. The new PID controller is tested in real life environment.

In the next paper on **A new encoding system for security engineering education, the authors have given** a macro-model for incremental rotary encoder. They have developed a design for circuits to produce signals. The simulations are produced using the designed encoder.

In the last paper on “**Secured Communications for networks with configuration and topology**”, the authors have produced a macro-model for incremental rotary encoder. This developed design is found to generate signals. With the help of the designed encoder, the simulation tests are carried out.

We hope that these papers may generate more interest.

## **Editors**